

## APPLICATION NOTE

# Mako U Triggering Concept

**Mako U cameras were discontinued in December 2020.**

**V2.0.0**  
2024-Oct-10

## Scope of this document

This document describes triggering basics **for Mako U** cameras, from best-practice rules to general examples.



### Triggering with Alvium USB cameras

Please see the Alvium USB Cameras User Guide at [www.alliedvision.com/en/support/technical-documentation/alvium-usb-documentation](http://www.alliedvision.com/en/support/technical-documentation/alvium-usb-documentation).



### Additional information for Mako U cameras

For the Mako U Technical Manual and the Mako U Cameras Features Reference, see [www.alliedvision.com/en/support/technical-documentation/mako-u-documentation](http://www.alliedvision.com/en/support/technical-documentation/mako-u-documentation).



### Features usage in programming

For information on programming with features, see the *Vimba Viewer Guide*, included in **Vimba**. See: <https://www.alliedvision.com/software>.

## Trigger signal flow

The following diagram shows the exposure of a frame started by an external signal. High levels show the active state of a signal. Proportions and dependencies are simplified to show the basic signal flow. Signal 1 starts Cycle 1.

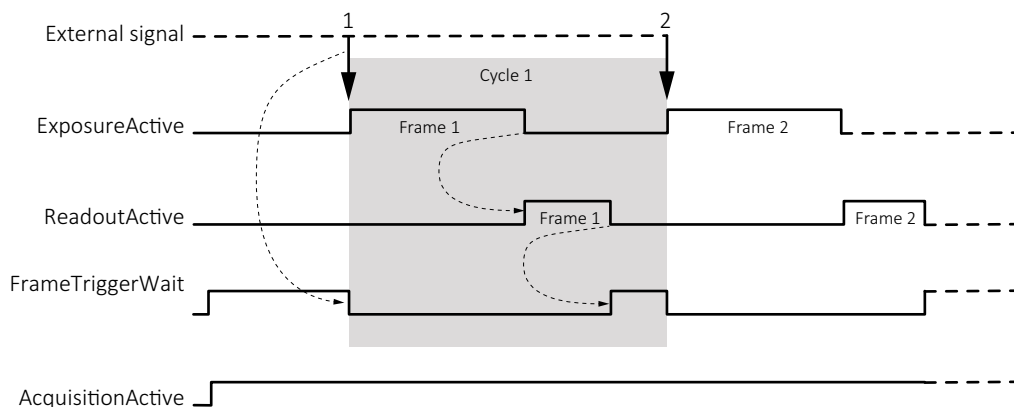


Figure 1: Trigger signal flow

Term	Description
External signal	Electrical trigger signal starting the signal flow
<i>ExposureActive</i>	Exposing a frame
<i>ReadoutActive</i>	Reading out a frame, high when the image sensor is reading out data
<i>FrameTriggerWait</i>	Waiting for a trigger
<i>AcquisitionActive</i>	<ul style="list-style-type: none"> <li>Acquiring of frames, needs to be high to start triggering</li> <li>High when the camera image sensor is either exposing, reading out data, or waiting for a trigger</li> </ul>

Table 1: Trigger signal flow, legend

## Trigger latency

Trigger latency is the time delay between the *FrameStart* trigger and the start of exposure. Trigger latency consists of:

- Jitter and delay of *ExposureStart*
- TriggerDelay*

Term	Description
<i>ExposureStart</i> jitter	<ul style="list-style-type: none"> <li>Deviation from the average periodical signal time</li> <li>Time range mainly caused by sensor line synchronization</li> </ul>
<i>ExposureStart</i> delay	<ul style="list-style-type: none"> <li>Deviation from the average periodical signal time</li> <li>Time range caused by camera internal timing</li> </ul>
<i>TriggerDelay</i>	Value set by the user to extend the trigger latency

Table 2: Trigger latency -> Components

## Best practice rules for triggering

- Set the trigger to *RisingEdge* for fastest possible reaction time.
- Set the trigger pulse width in the supported range.
- Consider that the end of exposure triggers the next readout.
- Make sure the exposure of a frame ends after the readout of the previous frame.
- Start exposure only between the readouts of two lines.
- Consider that  $ExposureStart\ delay = readout\ time - ExposureTime$ .

## Triggering when *ReadoutActive* is low

Apply *FrameStart* trigger when *ReadoutActive* is low. This way, you keep trigger latency (including *ExposureStart* jitter) short.

## Triggering when *ReadoutActive* is high

For fastest triggering cycle time with simultaneous exposure and readout, apply *FrameStart* trigger immediately when *FrameTriggerWait* is high. Because exposure must always begin at sensor line synchronization, the *ExposureStart* jitter can be up to 1 line cycle.

## Examples

### AcquisitionStart trigger and FrameStart trigger

#### AcquisitionStart description

To acquire images, *AcquisitionActive* must be high. Even to trigger the start of an acquisition by a pulse through an I/O, you have to issue an *AcquisitionStart* command.

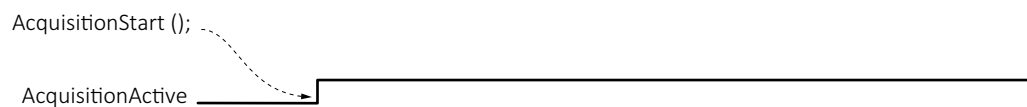


Figure 2: *TriggerMode = Off*, software command: *AcquisitionStart*

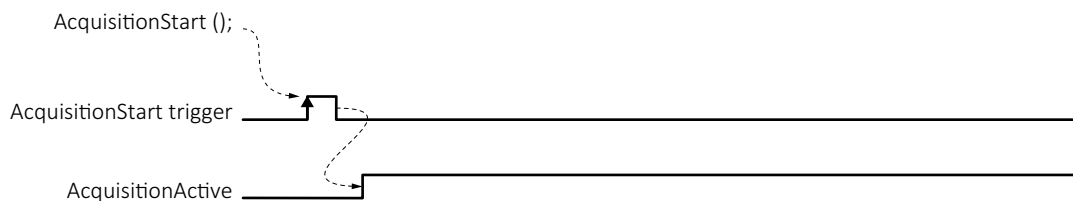


Figure 3: *TriggerMode = On*, software command: *AcquisitionStart*



#### **AcquisitionStop**

*AcquisitionStop* is mandatory to end acquisition.

With *AcquisitionMode = SingleFrame* or *MultiFrame*:

If no *AcquisitionStop* is signaled, after the selected number of frames has been acquired, the camera internally creates an *AcquisitionStop* command; this turns *AcquisitionActive* to low.

## AcquisitionStart trigger and FrameStart trigger dependencies

Figure 4 shows the dependencies between `AcquisitionStart` and `FrameStart` trigger.

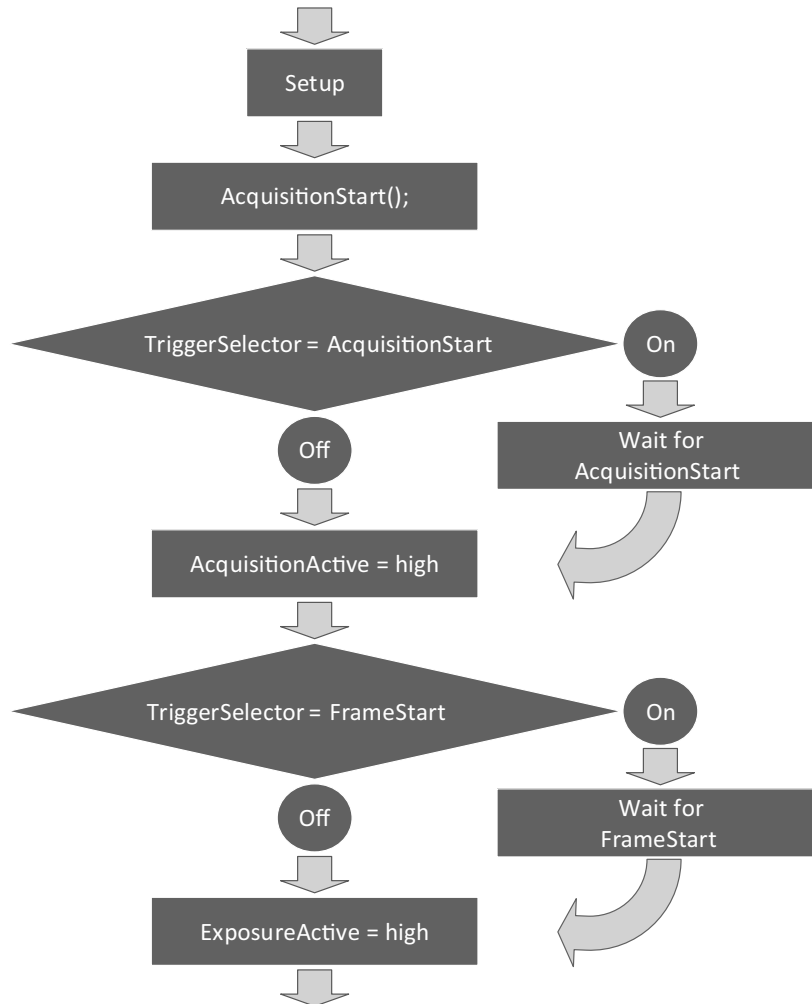


Figure 4: Dependencies of `AcquisitionStart` and `FrameStart`

## Modes for triggering

The following sections describe in general the main modes for triggering:

- `TriggerMode`
- `AcquisitionMode`
- `ExposureMode`

## TriggerSelector

The `TriggerSelector` examples in this section show triggering with `AcquisitionMode = Continuous`.

AcquisitionMode	TriggerSelector	
	AcquisitionStart	FrameStart
Continuous	Off	Off
Continuous	Off	On
Continuous	Off	Off
Continuous	Off	On

Table 3: `TriggerSelector` examples overview

An `AcquisitionStart` command sets `ExposureActive` to high. After this, the camera continues exposing with the maximum frame rate allowed. Maximum frame rate depends on factors, such as camera specifications and available bandwidth.

### Acquisition without triggering

If no trigger is selected, the `AcquisitionStart` command starts exposure.

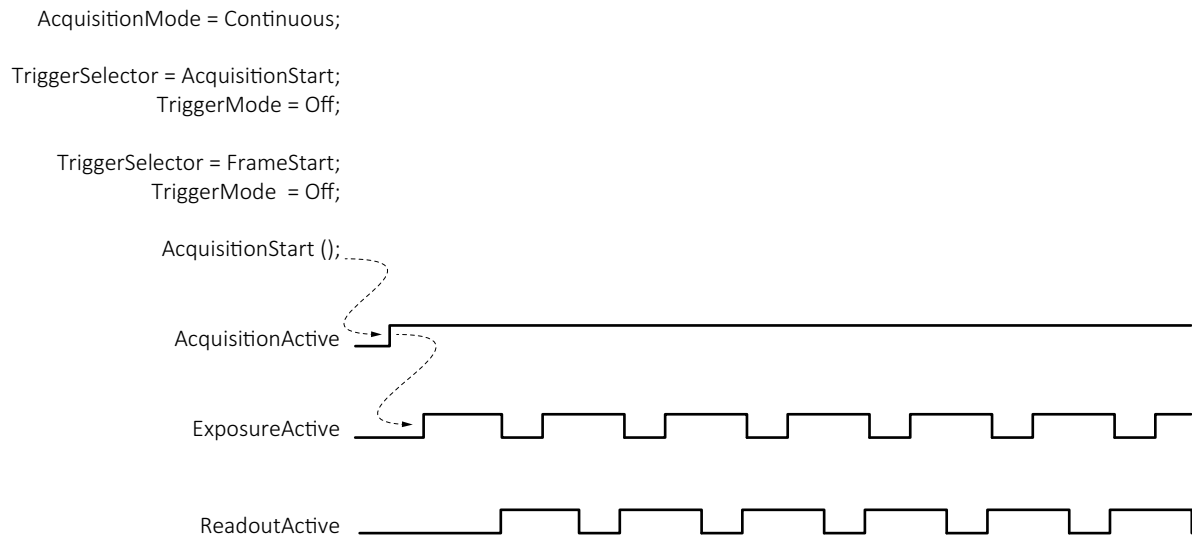


Figure 5: Acquisition without triggering

### TriggerSelector = FrameStart

*FrameStart* triggers the exposure.

```
AcquisitionMode = Continuous;  
TriggerSelector = AcquisitionStart;  
TriggerMode = Off;  
  
TriggerSelector = FrameStart;  
TriggerMode = On;
```

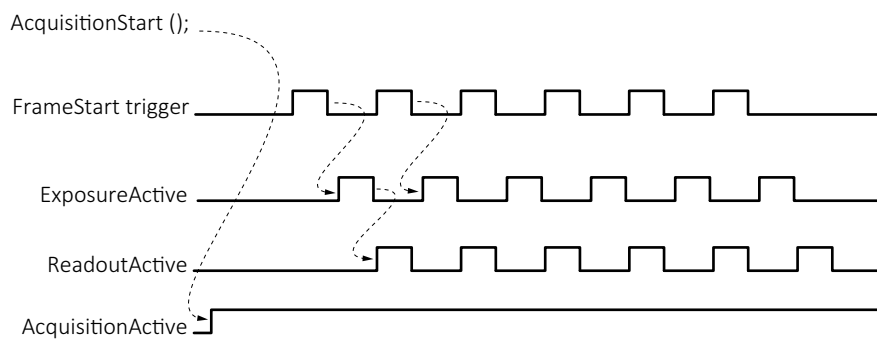


Figure 6: TriggerSelector = FrameStart trigger

## AcquisitionMode

### AcquisitionMode = SingleFrame

The `AcquisitionStart` command triggers the exposure of a single frame.

Every frame needs a separate `AcquisitionStart` command.

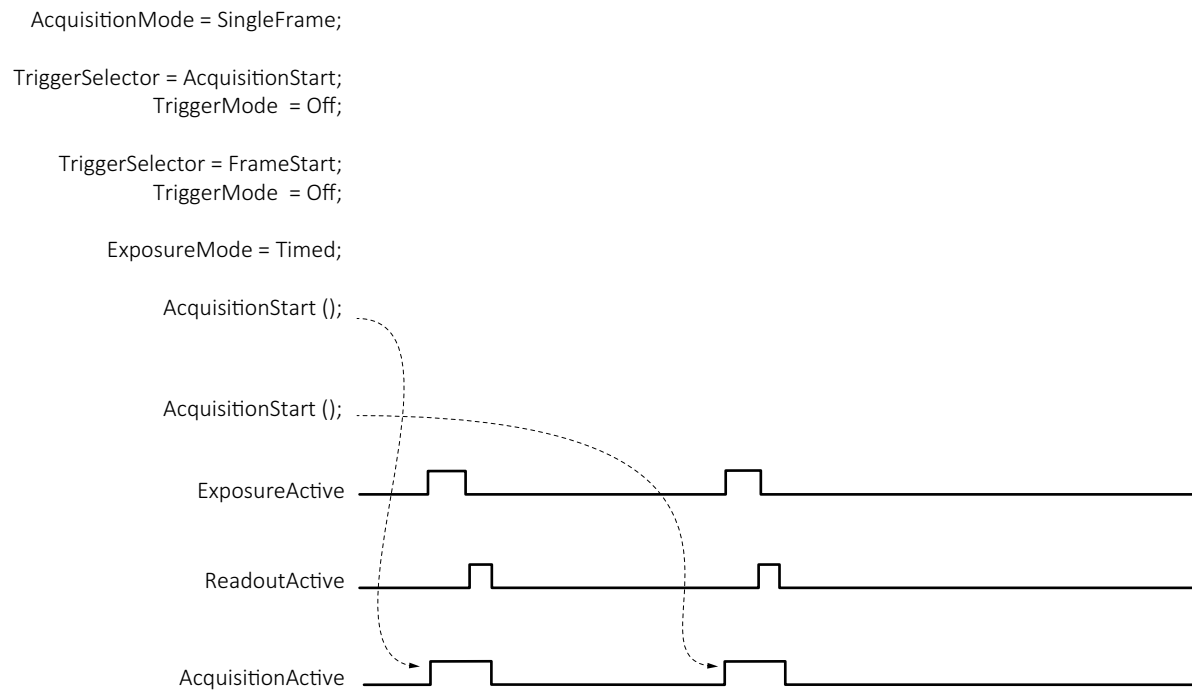


Figure 7: *AcquisitionMode = SingleFrame*

## AcquisitionMode = MultiFrame

`AcquisitionStart` triggers exposure.

`FrameCount` sets the number of images.

```
AcquisitionMode = MultiFrame;  
FrameCount = 6;
```

```
TriggerSelector = AcquisitionStart;  
TriggerMode = Off;
```

```
TriggerSelector = FrameStart;  
TriggerMode = Off;
```

```
ExposureMode = Timed;
```

```
AcquisitionStart ();
```

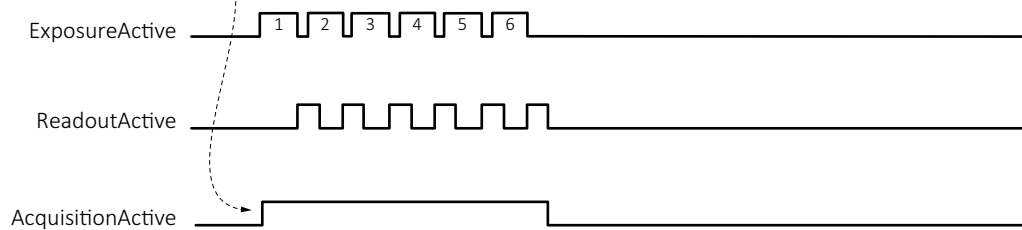


Figure 8: `AcquisitionMode = MultiFrame`



## ExposureMode

### ExposureMode = Timed

*FrameStart* triggers exposure.

*ExposureTime* sets exposure time.

```

AcquisitionMode = Continuous;

TriggerSelector = AcquisitionStart;
TriggerMode = Off;

TriggerSelector = FrameStart
TriggerMode = On;

ExposureMode = Timed;
ExposureTime = 500;

```

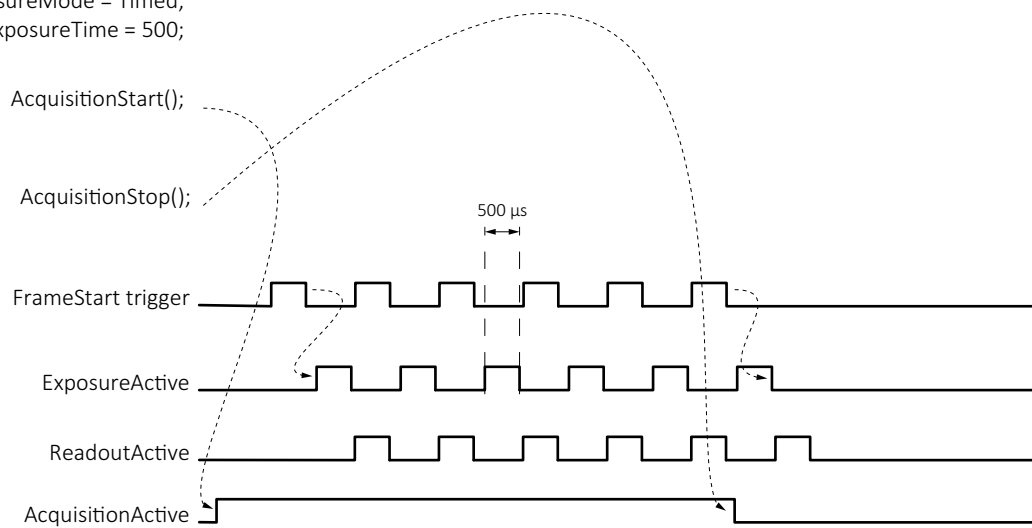


Figure 9: ExposureMode = Timed

## ExposureMode = TriggerWidth

*FrameStart* triggers exposure.

The duration of the *FrameStart* trigger sets the exposure time.

```
AcquisitionMode = Continuous;
```

```
TriggerSelector = AcquisitionStart;
TriggerMode = Off;
```

```
TriggerSelector = FrameStart
TriggerMode = On;
```

```
ExposureMode = TriggerWidth;
```

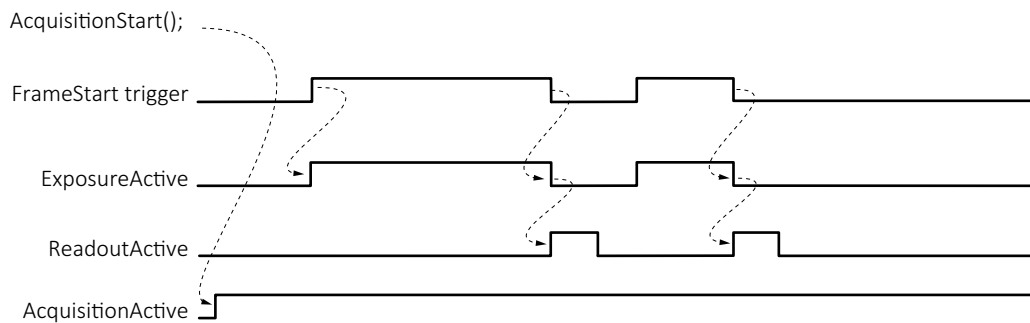


Figure 10: *ExposureMode = TriggerWidth*



### ExposureModes Mako U-503B

Mako U-503B provides only *Timed* value for *ExposureMode*.



### TriggerWidth and TriggerActivation

If the frame or line *TriggerActivation*[*TriggerSelector*] is *LevelHigh*, the camera exposes as long as the trigger is high.

If *TriggerActivation*[*TriggerSelector*] is *LevelLow*, the camera exposes as long as the trigger is low.

## Contact us

### Website, email

**General**

[www.alliedvision.com/en/contact](http://www.alliedvision.com/en/contact)  
[info@alliedvision.com](mailto:info@alliedvision.com)

**Distribution partners**

[www.alliedvision.com/en/avt-locations/avt-distributors](http://www.alliedvision.com/en/avt-locations/avt-distributors)

**Support**

[www.alliedvision.com/en/support](http://www.alliedvision.com/en/support)  
[www.alliedvision.com/en/about-us/contact-us/technical-support-repair-/rma](http://www.alliedvision.com/en/about-us/contact-us/technical-support-repair-/rma)

## Offices

**Europe, Middle East, and Africa  
(Headquarters)**

Allied Vision Technologies GmbH  
Taschenweg 2a  
07646 Stadtroda, Germany  
T// +49 36428 677-0 (Reception)  
T// +49 36428 677-230 (Sales)  
F// +49 36428 677-28

**North, Central, and South America, Canada**

Allied Vision Technologies Canada Inc.  
300 – 4621 Canada Way  
Burnaby, BC V5G 4X8, Canada  
T// +1 604 875 8855

**USA**

Allied Vision Technologies, Inc.  
102 Pickering Way- Suite 502  
Exton, PA 19341, USA  
Toll-free// +1-877-USA-1394  
T// +1 978 225 2030

**Asia-Pacific****China**

Allied Vision Technologies Shanghai Co Ltd.  
B-510, Venture International Business Park  
2679 Hechuan Road  
Minhang District, Shanghai 201103  
People's Republic of China  
T// +86 21 64861133

**Japan**

Allied Vision Technologies  
Yokohama Portside Bldg. 10F  
8-1 Sakae-cho, Kanagawa-ku  
Yokohama-shi, Kanagawa, 221-0052  
T// +81 (0) 45 577 9527

**Singapore**

Allied Vision Technologies Asia Pte. Ltd  
82 Playfair Rd, #07-01 D'Lithium  
Singapore 368001  
T// +65 6634 9027

## Copyright and trademarks

All text, pictures, and graphics are protected by copyright and other laws protecting intellectual property. All content is subject to change without notice. All trademarks, logos, and brands cited in this document are property and/or copyright material of their respective owners. Use of these trademarks, logos, and brands does not imply endorsement. Copyright © 2024 Allied Vision Technologies GmbH. All rights reserved.