



Alvium

1800 C-040c

- IMX287 CMOS sensor
- ALVIUM image processing
- MIPI CSI-2 interface
- Various hardware options

Hardware option: Open Housing CS-Mount

Alvium 1800 C – High-performance camera modules for embedded vision

Machine vision sensors for embedded system developers

Alvium 1800 C-040 with Sony IMX287 runs 302.0 frames per second at 0.4 MP resolution.

The powerful Alvium 1800 C MIPI CSI-2 camera series gives embedded system developers access to Sony's high-performance image sensors popular in the machine vision industry. These sensors with resolutions up to 20 megapixels deliver excellent image quality and up to twice the frame rates compared to similar Alvium 1500 C models.

To operate Alvium CSI-2 cameras on your vision system, Allied Vision provides different access modes: - **GenICam for CSI-2 Access** controls the camera by GenICam features, using the Alvium CSI-2 driver and CSI-2 transport layer (TL) directly. Currently, Alvium 1800 C-234, C-235, C-500, C-507, C-511, C-1236, and C-2050 are supported. Please find FAQs and installation instructions in the [Getting Started with GenICam for CSI-2](#) application note. - **Direct Register Access (DRA)** to control the cameras via registers for advanced users. - **Video4Linux2 Access** allows to control the cameras via established V4L2 API and applications like GStreamer and OpenCV. Open-source CSI-2 drivers are available on [GitHub](#) for different boards and system on chips (SoCs).

In addition to lens mount and housing options, see [Customization and OEM Solutions webpage](#) for additional options.

Specifications

| | |
|------------------------------------|---|
| Product code | 14215 |
| Interface | MIPI CSI-2, up to 4 lanes |
| Resolution | 728 (H) × 544 (V) |
| Spectral range | 300 to 1100 nm |
| Sensor | Sony IMX287 |
| Sensor type | CMOS |
| Shutter mode | GS (Global shutter) |
| Sensor size | Type 1/2.9 |
| Pixel size | 6.9 μm × 6.9 μm |
| Lens mount | CS-Mount |
| Optical Filter | Type Hoya C5000 IR cut filter |
| Max. frame rate at full resolution | 302 fps using 2 to 4 lanes, RAW8 (GREY) |
| ADC | 12 Bit |
| Image buffer (RAM) | 256 KByte |
| Non-volatile memory (Flash) | 1024 KByte |

Imaging performance

Imaging performance data is based on the evaluation methods in the EMVA 1288 Release 3.1 standard for characterization of image sensors and cameras. Measurements are typical values for monochrome models measured without optical filter.

| | |
|--------------------------------|-----------------------|
| Quantum efficiency at 529 nm | 64 % |
| Temporal dark noise | 3.2 e ⁻ |
| Saturation capacity | 208000 e ⁻ |
| Dynamic range | 74 dB |
| Absolute sensitivity threshold | 4.0 e ⁻ |

Output

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|--------------------------|---|
| Bit depth | 8-bit, 10-bit, 12-bit; Adaptive (10-bit, 12-bit) |
| Monochrome pixel formats | PFNC: Mono8, Mono10, Mono10p, Mono12, Mono12p CSI-2: RAW8, RAW10, RAW12 FOURCC: GREY, Y10, Y12 |

| | |
|-------------------------|---|
| YUV color pixel formats | PFNC: YCbCr411_8_CbYYCrYY, YCbCr422_8_CbYCrY, YCbCr8_CbYCr CSI-2: YUV422 8-bit FOURCC: UYVY |
| RGB color pixel formats | PFNC: RGB8 (default), BGR8 CSI-2: RGB888 (default) FOURCC: RGB3 |
| Raw color pixel formats | PFNC: BayerGR8, BayerGR10, BayerGR10p, BayerGR12, BayerGR12p |

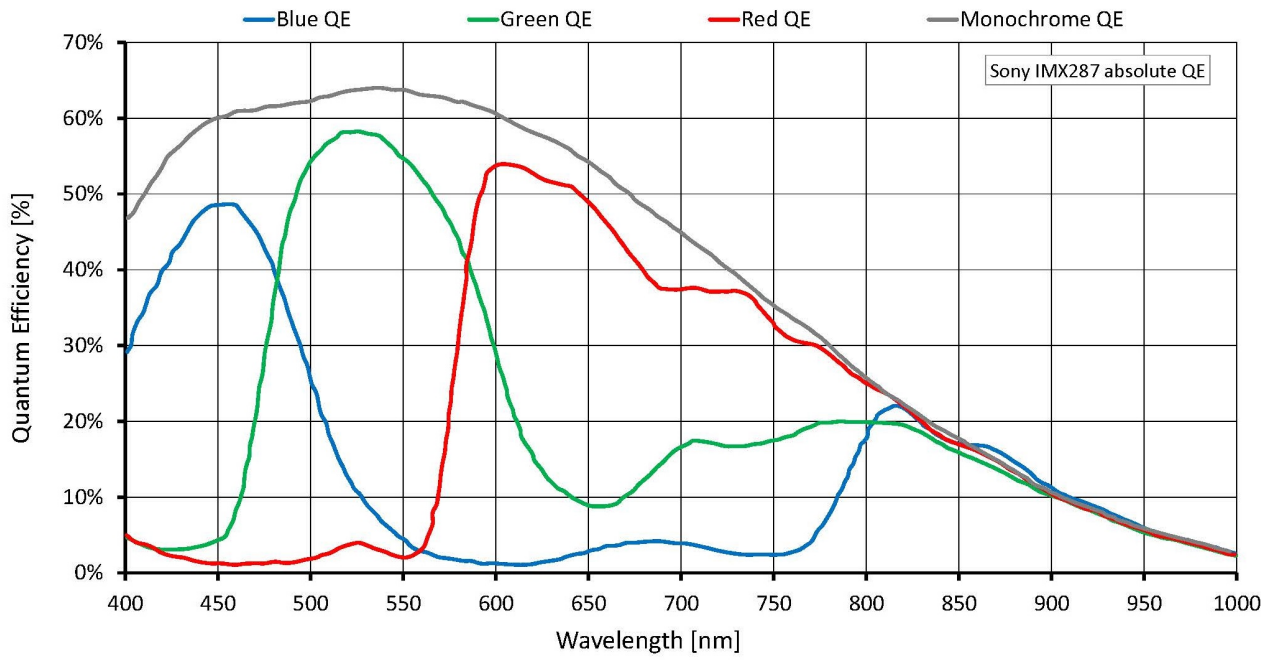
General purpose inputs/outputs (GPIOs)

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|----------|----------------------|
| TTL I/Os | 2 programmable GPIOs |
|----------|----------------------|

Operating conditions/dimensions

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|-----------------------------------|----------------------------|
| Operating temperature | -20 °C to +65 °C (housing) |
| Power requirements (DC) | 5 VDC over MIPI CSI-2 |
| Power consumption | Typical: 1.7 W |
| Mass | 40 g |
| Body dimensions (L × W × H in mm) | 21 × 29 × 29 |

Quantum efficiency



Features

Image control: Auto

- Auto exposure
- Auto gain
- Auto white balance (color models)

Image control: Other

- Black level
- Color transformation (incl. hue, saturation; color models)
- De-Bayering up to 5×5 (color models)
- DPC (defect pixel correction)
- FPNC (fixed pattern noise correction)
- Gamma
- Reverse X/Y
- ROI (region of interest)

Camera control

- Acquisition frame rate
- Firmware update in the field
- I/O and trigger control
- Temperature monitoring

Technical drawing

