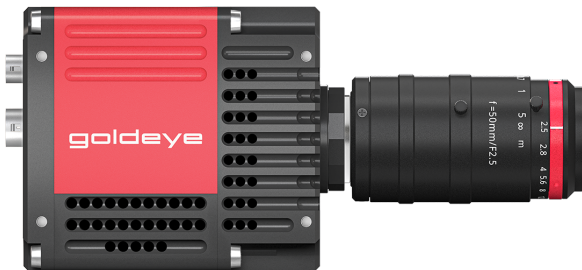


Goldeye

CL-034 TEC2



- Camera Link InGaAs camera
- VGA resolution
- Strong sensor cooling
- High dynamic range
- Low noise
- Fast frame rates: 303 fps

See the invisible

Short-wave infrared (SWIR) cameras with InGaAs sensor technology

Goldeye CL-034 TEC2 with FPA 636 × 508 | 15 μm | InGaAs runs 303.0 frames per second at 0.3 MP resolution.

Goldeye cameras are equipped with InGaAs sensor technology making them sensitive in the short wave infrared spectrum ranging from 900 nm to 1,700 nm. Some models have extended sensitivity in the visible spectrum down to 400 nm or up to 2200 nm. All Goldeye SWIR cameras can be operated at very high frame rates and capture outstanding low-noise images. They are the perfect choice for industrial and scientific applications beyond the visible spectrum. All Goldeye models are available with either a Camera Link or a GigE Vision interface.

Easy software integration with [Allied Vision's Vimba Suite](#) and compatibility to the most popular third party image-processing libraries.

[AcquireControl](#) adds extensive image analysis functions, such as:

- Pseudo color LUT with several color profiles
- Auto contrast
- Auto brightness
- Analyze multiple regions (rectangular, circle) within the image
- Real-time statistics and histogram display

The [Modular Concept](#) offers various options for lens mount, housing variants, optical filters, case design, and more. See the [Customization and OEM Solutions webpage](#) for additional options.

Specifications

Interface	Camera Link Base
Resolution	636 (H) × 508 (V)
Spectral range	900 nm to 1700 nm
Sensor	FPA 636 × 508 15 μm InGaAs
Sensor type	InGaAs
Sensor size	No standard size
Pixel size	15 μm × 15 μm
Lens mounts (available)	C-Mount
Max. frame rate at full resolution	303 fps
ADC	14 Bit
Image buffer (RAM)	256 MByte
Cooling temperature	-30 °C (default and calibrated) -20 °C, -10 °C (calibrated) 0 °C (uncalibrated) User configurable
Dark current	26 ke ⁻ /s (at -30 °C FPA temperature)
Temporal dark noise	390 e ⁻ (Gain0), 53 e ⁻ (Gain1), 32 e ⁻ (Gain2)
Saturation capacity	1.2 Me ⁻ (Gain0), 84.8 ke ⁻ (Gain1), 25 ke ⁻ (Gain2)
Dynamic range	69 dB (Gain0), 64 dB (Gain1), 59 dB (Gain2)

Output

Bit depth	8-bit to 16-bit
Monochrome pixel formats	Tap Geometry 1X 1Y: Mono8, Mono10, Mono12, Mono14, Mono16 Tap Geometry 1X2 1Y: Mono8, Mono10, Mono12

General purpose inputs/outputs (GPIOs)

TTL I/Os	LVTTL I/Os: 1 input, 1 output
Opto-isolated I/Os	1 input, 2 outputs
RS232	115 200 Baud, 8N1 (adjustable)

Operating conditions/dimensions

Operating temperature	-20 °C to +55 °C (housing)
Power requirements (DC)	10.8 V to 30.0 V

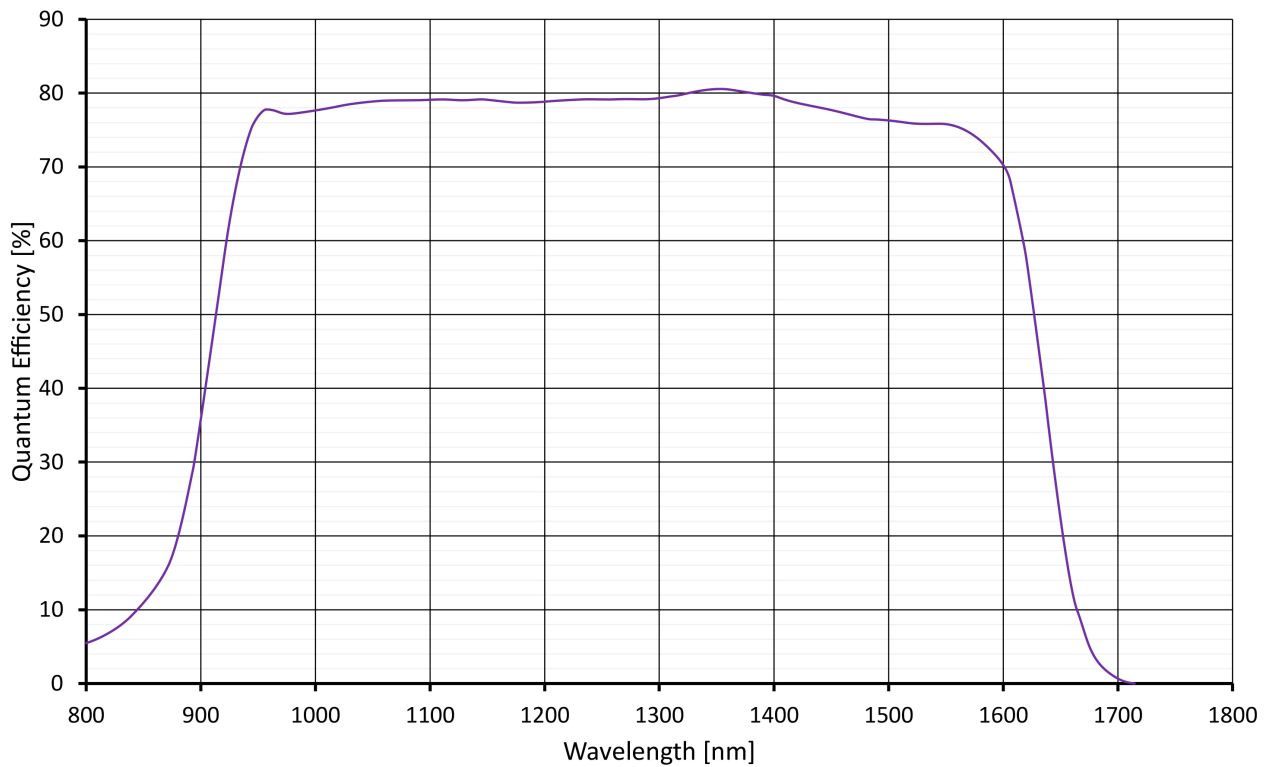
Power consumption 21 W at 12 VDC

Mass 740 g (with C-Mount adapter)

Body dimensions (L × W × H in mm) 90 × 80 × 80

Quantum efficiency

Goldeye G/CL-034 TEC2 Absolute QE



Features

Image control: Auto

- Auto contrast
- Auto exposure

Image control: Other

- Background correction
- Binning
- DPC (defect pixel correction)
- LUT (look up table)
- NUC (non-uniformity correction)
- ROI (region of interest)

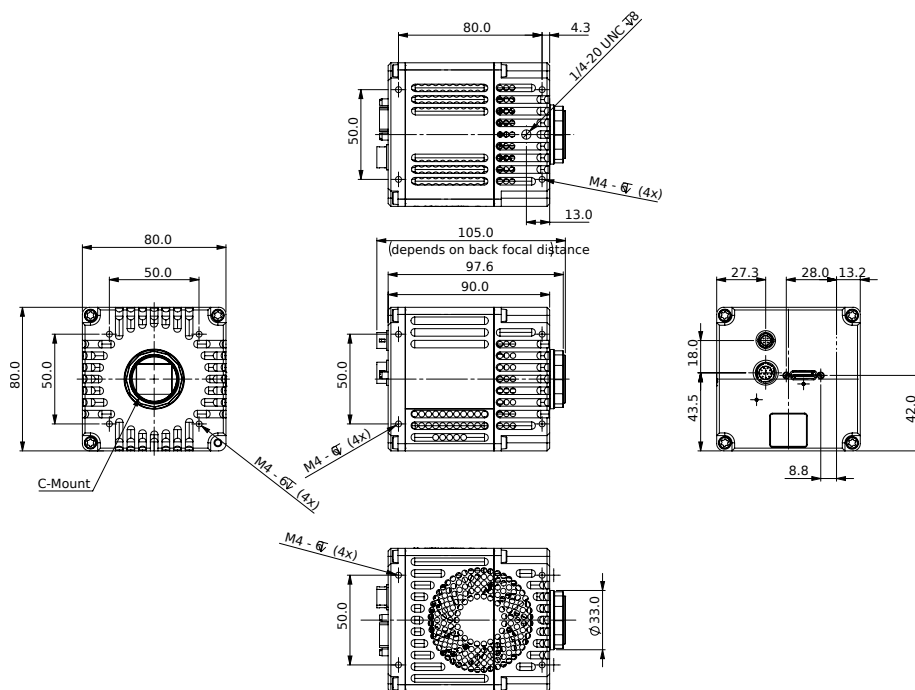
Camera control

- Acquisition frame rate
- Event channel
- Firmware update in the field
- I/O and trigger control
- Image chunk data
- Stream hold
- User sets

Sensor temperature control

- Temperature management by TEC
- Temperature status indicator

Technical drawing



Applications

Goldeye cameras are very sensitive in the SWIR spectrum. They can be used in an extended operating temperature range. Thanks to temperature stabilization and integrated image correction, Goldeye cameras achieve an outstanding image quality with little noise and a high dynamic range. They are well-suited for many typical SWIR applications in various industry branches:

- Semiconductor failure analysis
- Solar cell inspection
- Non-invasive in-vivo imaging (NIR-II)
- Fluorescence imaging
- Spectroscopy
- Microscopy
- Astronomy

White Paper To learn more about typical application fields for SWIR cameras, download our White Paper: [Seeing beyond the visible – short-wave infrared \(SWIR\) cameras offer new application fields in machine vision](#)